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a manual cut using the jog handle. On my machines with Oi-TC controls, I just single step a program until the spindle is turning then switch to 'handle jog' mode. When I try this on the Oi-TD I can't get the spindle to stay Fanuc Oi-TD Lathe question -

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inserting an existing program residing in the control memory or the PCMCIA card, most people resort to trial and error method. While they might be able to accomplish what they desire, the right approach would save a lot of their precious time.

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make the correct guess. The following excerpt from the book would give an idea of the methodical and step-by-step approach adopted in the book: Writing a file on the memory card: The following operation will save program number 1234 in

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the memory card,
with the name
TESTPRO: * Select
the EDIT mode on
the MOP panel. *
Press the PROG key
on the MDI panel. *
Press the next
menu soft key. *
Press the soft key
CARD. * Press the
soft key OPRT. *
Press the soft key
PUNCH. * Type

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1234 and press the soft key O SET. *

Type TESTPROG and press the soft key F NAME. *

Press the soft key EXEC. While the file is being copied on the memory card, the character string OUTPUT blinks at the lower right corner of the screen. Copying

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may take several seconds, depending on the size of the file being copied. If a file with file name TESTPROG already exists in the memory card, it may be overwritten unconditionally or a message confirming the overwriting may be

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displayed,
depending on a
parameter setting.
In case of such a
warning message,
press the EXEC soft
key to overwrite,
and CAN soft key
to cancel writing.
However, system
information such as
PMC ladder is
always overwritten
unconditionally.

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The copied file is automatically assigned the highest existing file number plus one. The comment, if any, with the O-word (i.e., in the first block of the program) will be displayed in the COMMENT column of the card directory. To write

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all programs, type

-9999 as the

program number.

In this case, if file

name is not

specified, all the

programs are

saved in file name

PROGRAM.ALL on

the memory card.

A file name can

have up to 8

characters, and an

extension up to 3

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Character

(XXXXXXXXX.XXX).

Repeat the last three steps to copy more files. Finally, press the CAN soft key, to cancel the copying mode and go to the previous menu.

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the InternetIndex

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and utility of robots
has increased
dramatically with
new technology,
robotic systems
can perform tasks

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that are physically dangerous for humans, repetitive in nature, or require increased accuracy, precision, and sterile conditions to radically minimize human error. The Robotics and Automation Handbook addresses the

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major aspects of designing, fabricating, and enabling robotic systems and their various applications. It presents kinetic and dynamic methods for analyzing robotic systems, considering factors such as force and

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torque. From these analyses, the book develops several controls

approaches, including servo actuation, hybrid control, and trajectory planning.

Design aspects include

determining specifications for a robot, determining

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its configuration,
and utilizing
sensors and
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featured
applications focus
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The authors are all
involved in cutting-
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their respective
fields of
specialization. The
integration of
manufacturing
constraints and
their optimization
in the design
process is
becoming more
and more
widespread in the
development of
mechanical

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products or

systems. There is a

clear industrial

need for these

kinds of

methodologies.

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unsolved -

problems are

related to the

definition of design

processes, the

choice of optimal

manufacturing

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processes, and their integration through coherent methodologies in adapted environments. The main topics addressed in this book are: analysis and optimization of mechanical parts and products (computational structural

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the relation
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